

Manolescu's Seiberg-Witten Floer homotopy type

Nobuhiro Nakamura

The University of Tokyo

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Introduction

Seiberg-Witten Floer stable homotopy types

- Seiberg-Witten trajectories

- Finite dimensional approximation

- The Conley index

- Construction of the invariant

Relative Bauer-Furuta invariants

Gluing formula for relative BF invariants

- S-duality for Conley indices

- Gluing formula

- Cobordism

Applications

Introduction

Morse homology

M : manifold,
 $f : M \rightarrow \mathbb{R}$, Morse function
 } $\rightarrow H^*(M)$.

Floer homology

∞ -dim. Morse homology

- ▶ Gauge theory
 - ▶ Chern-Simons functional $CS : \mathcal{A} \rightarrow \mathbb{R}$
 → Instanton homology $HF(Y)$
 - ▶ Chern-Simons-Dirac functional $CSD : \mathcal{C} \rightarrow \mathbb{R}$
 → Seiberg-Witten Floer homology $HF^{SW}(Y)$
- ▶ Symplectic → Hamiltonian, Lagrangian
- ▶ Heegaard Floer homology

- ▶ Finite dim. Morse theory
 Morse function → CW complex structure of M .

- ▶ Floer theory

→ What is the underlying topological structure?

- ▶ [Fukaya]... → Morse homotopy
- ▶ [Cohen-Jones-Segal] → Floer homotopy type

[Manolescu]

In the Seiberg-Witten Floer case, (Y : 3-manifold with $b_1 = 0$ or 1,) it is defined a pointed S^1 -space (prespectrum) $SWF(Y)$ s.t.

$$H_*(SWF(Y)) \cong HF_*^{SW}(Y).$$

Idea

- Gauge group = $U(1)$.
- The compactness of the moduli. } → Finite dimensional approximation
- The Conley index

Cf. [Frauenfelder '04] → Moment Floer homology.

[Cohen '07] → Hamiltonian Floer homology of the cotangent bundle

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Contents

- ▶ Definition of Seiberg-Witten Floer stable homotopy types
- ▶ Relative Bauer-Furuta invariants
- ▶ Gluing formula for relative BF invariants.
- ▶ Applications

Seiberg-Witten Floer stable homotopy types

- ▶ Seiberg-Witten trajectories
- ▶ Finite dimensional approximations
- ▶ The Conley index
- ▶ Construction of the invariants

Seiberg-Witten trajectories

- ▶ Y : oriented closed 3-manifold, g : metric.
- ▶ c : Spin^c -structure.
 → W_0 : the spinor bundle, $L = \det W_0$.
- ▶ If $b_1 = 0$, $\Rightarrow \exists$ flat connection A_0 on L unique up to gauge.
 → $\partial_0: \Gamma(W_0) \rightarrow \Gamma(W_0)$, Dirac operator.
- ▶ $\mathcal{A}(L) := \{\text{U}(1)\text{-connections on } L\} = A_0 + i\Omega^1(Y)$.
- ▶ For $A = A_0 + a$
 → $\partial_a = \rho(a) + \partial_0$, the Dirac op. associated to A ,
 where $\rho(a)$ is the Clifford multiplication.

- ▶ $\mathcal{G} = \text{Map}(Y, S^1) \curvearrowright \mathcal{C} := i\Omega^1(Y) \oplus \Gamma(W_0)$ by

$$u(a, \phi) = (a - 2u^{-1}du, u\phi).$$

- ▶ Fix $k \geq 4$.
 $\mathcal{G} \leftarrow L^2_{k+2}$ -completion
 $\mathcal{C} \leftarrow L^2_{k+1}$ -completion
- ▶ Chern-Simons-Dirac functional, $CSD: \mathcal{C} \rightarrow \mathbb{R}$,

$$CSD(a, \phi) = \frac{1}{2} \left(- \int_Y a \wedge da + \int_Y \langle \phi, \partial_a \phi \rangle d \text{vol} \right).$$

- ▶ If $b_1 = 0 \Rightarrow$ CSD is \mathcal{G} -invariant.

$$CSD(u(a, \phi)) = CSD(a, \phi).$$

SWF homology = the Morse homology of CSD

The SWF homotopy type is defined as a **Conley index** for CSD via finite dimensional approximations:

$$CSD \longrightarrow (\text{finite dim. approx}) \longrightarrow \text{Conley index } SWF(Y, c).$$

Then,

$$\begin{aligned} \tilde{H}_*(SWF(Y, c)) &\cong \text{the Morse homology of } CSD \\ &\cong \text{the SWF homology for } (Y, c). \end{aligned}$$

The gradient vector field of CSD w.r.t. L^2 -metric

$$\nabla CSD(a, \phi) = (*da + \tau(\phi, \phi), \partial_a \phi).$$

$$\nabla CSD(a, \phi) = 0 \Leftrightarrow \text{3-dim. Seiberg-Witten eqns on } (Y, c)$$

$$\text{Crit}(CSD) = \{\text{solutions to SW}\}.$$

Seiberg-Witten trajectories

= trajectories of the downward grad. flow of CSD .

$$x = (a, \phi): \mathbb{R} \rightarrow \mathcal{C},$$
$$\frac{\partial}{\partial t} x(t) = -\nabla CSD(x(t)) \cdots (\star)$$

$(\star) \Leftrightarrow$ 4-dim. Seiberg-Witten eqns on $Y \times \mathbb{R}$

Definition

A SW-trajectory $x(t)$ is **of finite type**

$\stackrel{\text{def}}{\Leftrightarrow} CSD(x(t))$ & $\|\phi_t\|_{C^0}$ are bounded functions in t .

Proposition (Compactness)

$\forall m \in \mathbb{Z}_{>0} \exists C_m \forall$ finite type traj. $x(t) = (a_t, \phi_t)$ s.t.

$$\forall t \exists u_t \in \mathcal{G}, \|u_t(a_t, \phi_t)\|_{C^m} \leq C_m.$$

Projection to the Coulomb gauge

- ▶ CSD is \mathcal{G} -invariant \Rightarrow Want to consider $CSD|_{\mathcal{G}}: \mathcal{C}/\mathcal{G} \rightarrow \mathbb{R}$.
- ▶ Instead of dividing by \mathcal{G} , project to the slice at $(0, 0)$.

$$\mathcal{G}_0 := \left\{ u = e^{i\xi} \mid \xi: Y \rightarrow \mathbb{R}, \int_Y \xi = 0 \right\},$$

$$\mathcal{G}_0 \curvearrowright \mathcal{C} \text{ free,}$$

$$\mathcal{G}/\mathcal{G}_0 = S^1 \leftarrow \text{the stabilizer of } (0, 0).$$

- $V := i \ker d^* \oplus \Gamma(W_0)$. \leftarrow The slice at $(0, 0)$

$$\Rightarrow \forall (a, \phi) \in \mathcal{C}, \exists_1 u \in \mathcal{G}_0, u(a, \phi) \in V.$$

- ▶ This gives the **Coulomb projection** $\Pi: \mathcal{C} \rightarrow V$.

- ▶ Choose a metric \tilde{g} on V s.t.

$$\Pi' \circ \nabla^{L^2}(CSD) = \nabla^{\tilde{g}}(CSD|_V),$$

where $\Pi' =$ the differential of Π . Then,

$$\Pi\text{-projection of } \nabla^{L^2}(CSD) \text{ trajectory} \leftrightarrow \text{Traj. of } \nabla^{\tilde{g}}(CSD|_V).$$

- Note $\nabla^{\tilde{g}}(CSD|_V)$ is S^1 -equivariant.
- ▶ Decompose $\nabla^{\tilde{g}}(CSD|_V)$ as $\nabla^{\tilde{g}}(CSD|_V) = l + c$, where
 - ▶ l : linear, $l(a, \phi) = (*da, \partial_0\phi)$,
 - ▶ c : quadratic, compact.
- ▶ We concentrate on trajectories

$$x: \mathbb{R} \rightarrow V, \frac{\partial}{\partial t} x(t) = -(l + c)(x(t)).$$

Finite dimensional approximation

- ▶ $I(a, \phi) = (*da, \partial_0 \phi)$: self-adjoint \Rightarrow has **real eigenvalues**.

$$V_\lambda^\mu := \bigoplus_{\nu \in (\lambda, \mu]} \ker(I - \nu \text{id}_V),$$

$$\tilde{p}_\lambda^\mu: V \rightarrow V_\lambda^\mu (\subset V). \leftarrow L^2\text{-projection}$$

- ▶ When varying λ & μ , \tilde{p}_λ^μ may jump.
 \Rightarrow **smoothing**

$$p_\lambda^\mu: V \rightarrow V.$$

- ▶ **Finite dimensional approximation** of SW-trajectory is given by,

$$x: \mathbb{R} \rightarrow V_\lambda^\mu,$$
$$\frac{\partial}{\partial t} x(t) = -(I + p_\lambda^\mu c)x(t).$$

- ▶ By Compactness Proposition,

$$\exists R \gg 1, \text{ s.t. } (\forall \text{ finite type traj. of } I + c) \subset B(R),$$

where $B(R)$ is the open ball in $L^2_{k+1}(V)$ with radius R centered at 0.

Fix such an R .

Proposition

For sufficient large $-\lambda$ & μ ,
 $x(t)$: a trajectory of $I + p_\lambda^\mu c$,

$$\forall t, x(t) \in \overline{B(2R)} \Rightarrow \forall t, x(t) \in B(R).$$

Next, Gradient flows of $I + p_\lambda^\mu c \Rightarrow$ Conley index.

The Conley index

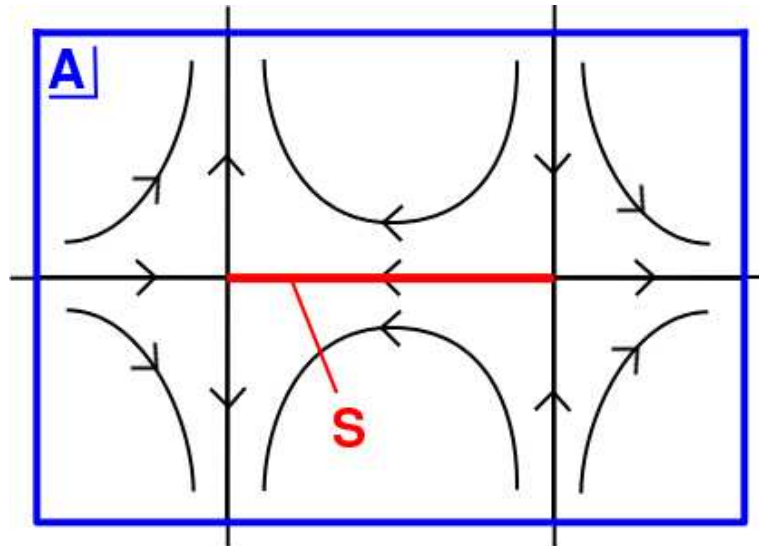
- ▶ M : finite dim. manifold
- ▶ $\varphi: M \times \mathbb{R} \rightarrow M$, a continuous flow, $\begin{cases} \varphi_0 = \text{id}, \\ \varphi_{s+t} = \varphi_s \circ \varphi_t. \end{cases}$
- ▶ $S(\subset M)$ is **invariant** $\stackrel{\text{def}}{\Leftrightarrow} \forall t \varphi_t(S) = S$.
- ▶ For $A(\subset M)$, **the invariant set of A** is,

$$\text{Inv}(A) := \bigcap_t \varphi_t(A) = \{x \in A \mid \forall t \varphi_t(x) \in A\}.$$

► A compact subset $S \subset M$ is an **isolated invariant set** if

$$\exists \text{ cpt set } A \text{ s.t. } S = \text{Inv}(A) \subset \text{Int}(A).$$

A is called an isolating neighborhood.



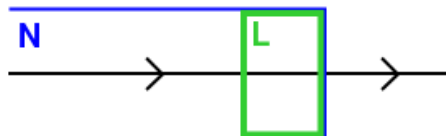
Definition

A pair of compact sets (N, L) , $L \subset N \subset M$, is an **index pair** for an inv. set S if

- $S = \text{Inv}(N \setminus L) \subset \text{Int}(N \setminus L)$.

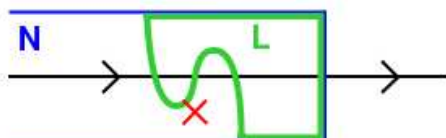
- L is an **exit set**:

$$\forall x \in N, \forall t > 0 \text{ s.t. } \varphi_t(x) \notin N \Rightarrow \exists \tau \in [0, t) \varphi_\tau(x) \in L.$$

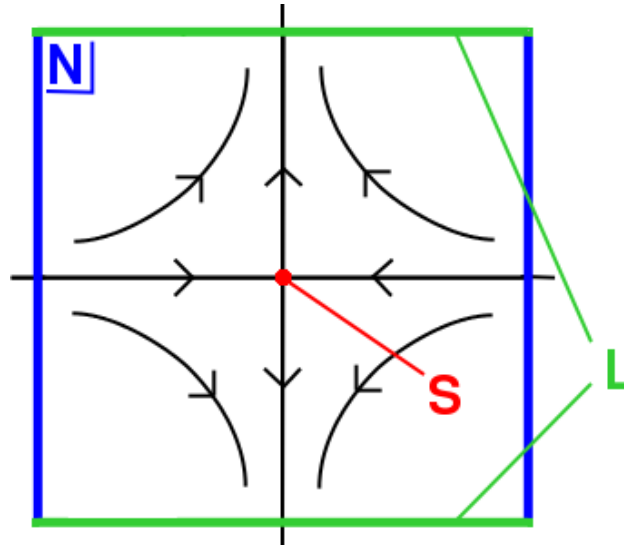


- L is **positively invariant**:

$$x \in L, t > 0, \varphi_{[0,t]}(x) \subset N \Rightarrow \varphi_{[0,t]}(x) \subset L.$$



An example of index pair



Theorem (Conley)

For every iso. inv. set S & isolating nbd. A ,

$$\exists \text{ index pair } (N, L) \text{ for } S \text{ s.t. } N \subset A.$$

Definition

The **Conley index** of S is,

$$I(\varphi, S) := \text{the pointed homotopy type of } (N/L, [L]).$$

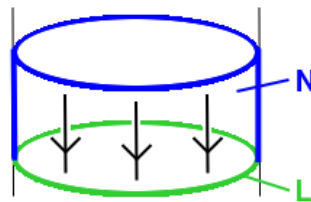
Properties

- ▶ $I(\varphi, S)$ is independent of the choice of (N, L) .
- ▶ (Continuation)
 φ^λ ($\lambda \in [0, 1]$): continuous family of flows.
 S^λ : invariant sets for φ_λ .
 If $\forall \lambda$ A is an isolating nbd. of S_λ , i.e., $\text{Inv}(A) = S^\lambda$,

$$\Rightarrow I(\varphi^0, S^0) \cong I(\varphi^1, S^1).$$

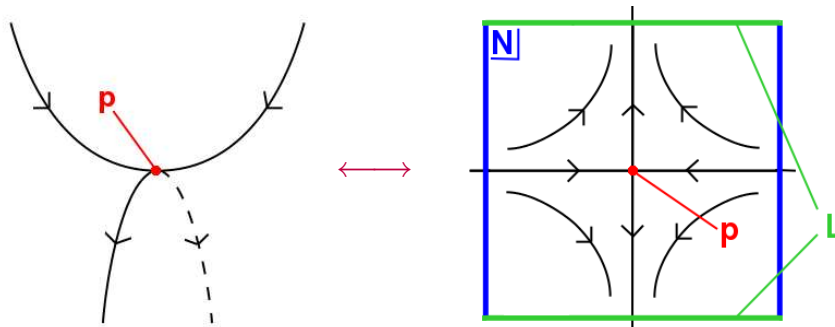
Examples

1. $I(\varphi, \emptyset) = \{1\text{pt}\}$



2. If p is a crit. point of a grad. flow with $\text{index}=k$,

$$I(\varphi, \{p\}) \cong S^k.$$



3. M : closed,
 $f: M \rightarrow \mathbb{R}$, Morse function s.t. Morse-Smale,
 $S := \{\text{Crit. points of } f \text{ \& trajectories between them}\}$

$$\Rightarrow \tilde{H}_*(I(\varphi, S)) \cong \text{the Morse homology of } f.$$

Theorem (Floer et al.)

- ▶ G : a compact Lie group,
- ▶ $G \curvearrowright M$ preserving φ_t ,
- ▶ S : a G -invariant iso. inv. set.

Then, the G -equivariant Conley index $I_G(\varphi, S)$ is defined as a pointed G -homotopy type.

Construction of the invariant

Finite dim. approx. $x: \mathbb{R} \rightarrow V_\lambda^\mu$ is “stable” when $-\lambda$ & $\mu \rightarrow \infty$.

⇒ The Conley index is also **stable**.

⇒ **SWF**(Y, c) is defined as an object in a certain stable homotopy category.

Let S^1 act on \mathbb{R} & \mathbb{C} as:

- ▶ $S^1 \curvearrowright \mathbb{R}$: trivially
- ▶ $S^1 \curvearrowright \mathbb{C}$: by multiplication.

Definition

\mathcal{C} is S^1 -equivariant graded suspension category as follows:

- ▶ **Object:** (X, m, n)
 X : pointed S^1 -space, $m \in \mathbb{Z}$, $n \in \mathbb{Q}$.
- ▶ **Morphism:**

$$\{(X, m, n), (X', m', n')\}_{S^1} = \begin{cases} \emptyset & \text{if } n - n' \notin \mathbb{Z}, \\ \operatorname{colim}_{k,l} \left[(\mathbb{R}^k \oplus \mathbb{C}^l)^+ \wedge X, (\mathbb{R}^{k+m-m'} \oplus \mathbb{C}^{l+n-n'})^+ \wedge X' \right]_{S^1}, & \text{if } n - n' \in \mathbb{Z}. \end{cases}$$

Note: $(X, m, n) \cong (\mathbb{R}^+ \wedge X, m+1, n) \cong (\mathbb{C}^+ \wedge X, m, n+1)$.

$$\begin{aligned} (X, m, n) &\mapsto (X, m-1, n) \cong (\mathbb{R}^+ \wedge X, m, n) \\ (X, m, n) &\mapsto (X, m, n-1) \cong (\mathbb{C}^+ \wedge X, m, n) \end{aligned}$$

- ▶ $m \mapsto m + 1 \leftrightarrow$ (formal) desuspension by \mathbb{R}^+
- ▶ $n \mapsto n + 1 \leftrightarrow$ (formal) desuspension by \mathbb{C}^+
- ▶ Denote $(X, 0, 0)$ by X .
- ▶ For a finite dim. vector space E with trivial S^1 -action,

$$\Sigma^{-E}X := (E^+ \wedge X, 2 \dim_{\mathbb{R}} E, 0).$$

- ▶ For a finite dim. vector space E with free S^1 -action except 0,

$$\Sigma^{-E}X := (X, 0, \dim_{\mathbb{C}} E).$$

- ▶ **Recall** our situation.

$$\left. \begin{array}{l} x: \mathbb{R} \rightarrow V_{\lambda}^{\mu}, \\ \frac{\partial}{\partial t} x(t) = -(I + p_{\lambda}^{\mu} c)x(t), \end{array} \right\} \longrightarrow \text{gradient flow } \varphi_{\mu}^{\lambda}.$$

- ▶ Define the isolated invariant set S_{λ}^{μ} by

$$\begin{aligned} S_{\lambda}^{\mu} &:= \text{Inv}(V_{\lambda}^{\mu} \cap \overline{B(2R)}) \\ &= \{\text{Crit. points in } B(R) \text{ \& trajectories connecting them}\} \end{aligned}$$

$$\longrightarrow I_{\lambda}^{\mu} = I_{S^1}(\varphi_{\mu}^{\lambda}, S_{\lambda}^{\mu}).$$

Definition

$$\text{SWF}(Y, c) := \left(\Sigma^{-V_\lambda^0} I_\lambda^\mu, 0, n(Y, c, g) \right),$$

where $n(Y, c, g)$ is a rational number determined from eta invariants of Dirac & sign.

Why $\Sigma^{-V_\lambda^0} I_\lambda^\mu$ & what is $n(Y, c, g)$?

Morse index of the reducible $(0, 0) = \#\{\text{negative eigenvalues}\}$
 $= \dim V_\lambda^0$. ← depending on λ, g

$$\Rightarrow \Sigma^{-V_\lambda^0} I_\lambda^\mu$$

- g_t : path of metric $g_0 \xrightarrow{g_t} g_1$.
- If λ is not eigenvalue for $\forall g_t$,

$$\begin{aligned} \Rightarrow \dim(V_\lambda^0)_{g_1} - \dim(V_\lambda^0)_{g_0} &= SF((\partial)_{g_t}) \\ &= n(Y, c, g_1) - n(Y, c, g_0). \end{aligned}$$

$$\Rightarrow \Sigma^{-V_\lambda^0 - \mathbb{C}n(Y, c, g)} I_\lambda^\mu$$

Theorem

$\text{SWF}(Y, c) = \Sigma^{-V_\lambda^0 - \mathbb{C}^{n(Y, c, g)}} I_\lambda^\mu$ is independent of parameters.

Example

If Y admits a metric of positive scalar curvature

\Rightarrow The reducible θ is the unique solution.

$\Rightarrow S_\lambda^\mu = \{\theta\}$. $\Rightarrow I_\lambda^\mu = (V_\lambda^0)^+$.

$\Rightarrow \text{SWF}(Y, c) = \left(\mathbb{C}^{-n(Y, c, g)} \right)^+$.

▶ $Y = S^3 \Rightarrow \text{SWF}(Y) = S^0$.

▶ $Y = \text{Poincaré sphere} \Rightarrow \text{SWF}(Y) = \mathbb{C}^+$.

Relative Bauer-Furuta invariants

First, we recall ordinary Bauer-Furuta invariants.

Bauer-Furuta invariants

Bauer-Furuta invariant is a stable cohomotopy refinement of the Seiberg-Witten invariant defined by [Bauer-Furuta].

▶ X : closed ori. 4-mfd. For simplicity, suppose $b_1 = 0$.

▶ \hat{c} : Spin^c -structure on X .

▶ Fix a connection \hat{A}_0 on the determinant line bundle $\det \hat{c}$ of \hat{c} .

▶ Monopole map

$$SW: i \ker d^*(\mathbb{C} \otimes i\Omega^1(X)) \oplus \Gamma(W^+) \rightarrow i\Omega^+(X) \oplus \Gamma(W^-)$$

$$(\hat{a}, \hat{\phi}) \mapsto (F_{\hat{A}_0 + \hat{a}}^+ + \sigma(\hat{\phi}, \hat{\phi}^*), D_{\hat{A}_0 + \hat{a}} \hat{\phi})$$

▶ Decompose SW as

$$SW = L + C,$$

where L : linear & C : quadratic, compact.

▶ Take a finite dim. approx. of $L + C$:

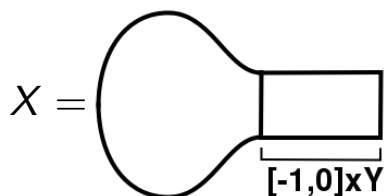
$$L + p^\nu C: U' \rightarrow U.$$

▶ The Bauer-Furuta invariant $BF_X(c)$ is defined as

$$BF_X(c) = [L + p^\nu C] \in \left\{ \left(\mathbb{C}^{\text{ind}_c D_{\hat{A}_0}} \right)^+, \left(\mathbb{R}^{b^+} \right)^+ \right\}_{S^1}.$$

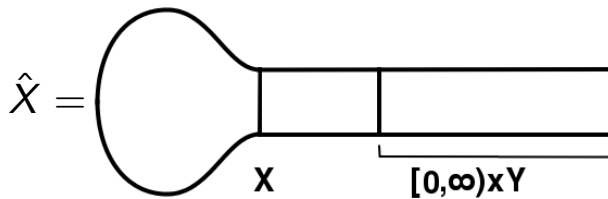
Relative Bauer-Furuta invariants

- ▶ Y : closed ori. 3-manifold, $b_1(Y) = 0$.
- ▶ X : compact ori. 4-manifold, $\partial X = Y$.
 For simplicity, $b_1(X) = 0$.
- ▶ Fix a metric \hat{g} as in the picture below.
- ▶ \hat{c} : Spin^c -structure on X . $\rightarrow c := \hat{c}|_Y$, a Spin^c -str. on Y .
- ▶ Fix a connection \hat{A}_0 on $\det \hat{c}$ s.t. $A_0 := \hat{A}_0|_Y$ is a flat conn. on $\det c$.



(Ordinary) relative SW-invariants (a rough sketch)

- ▶ Let $\hat{X} = X \cup_Y [0, \infty) \times Y$:



- ▶ Consider L^2 -moduli $\mathcal{M}^{L^2}(\hat{X}, \hat{c})$.

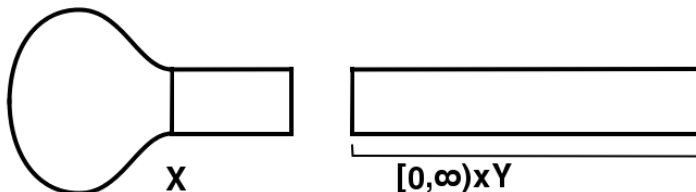
$$\partial_\infty : \mathcal{M}^{L^2}(\hat{X}, \hat{c}) \rightarrow \mathcal{M}(Y, c) = \text{Crit}(CSD).$$

- ▶ Note $HF_*^{SW}(Y, c)$ is generated by crit pts of CSD .
- ▶ Relative SW-invariant $\Psi_{X, \hat{c}} \in HF_*^{SW}(Y, c)$,

$$\Psi_{X, \hat{c}} := \sum_{a \in \text{Crit}(CSD)} \#(\partial_\infty^{-1}(a)) \langle a \rangle \in HF_*^{SW}(Y, c)$$

The Idea for relative BF invariants

- ▶ Decompose \hat{X} into X and the cylinder of Y :



- ▶ Then,

$$\begin{aligned} & \text{A SW-solution } (\hat{A}, \hat{\phi}) \text{ on } \hat{X} \\ &= (\hat{A}, \hat{\phi})|_X + \left(\text{a flow } x(t) \text{ on } V \text{ with } x(0) = (\hat{A}, \hat{\phi})|_{\{0\} \times Y} \right). \end{aligned}$$

Monopole map

- ▶ $\Omega_{\hat{g}}^1(X) := \{\hat{a} \in \Omega^1(X) \mid \hat{a} \in \ker d^*, \hat{a}|_{\partial X}(\nu) = 0\}$,
 where ν : the unit normal vector to the boundary Y .
- ▶ Fix a large μ .
- ▶ **Monopole map**

$$SW: i\Omega_{\hat{g}}^1(X) \oplus \Gamma(W^+) \rightarrow i\Omega^+(X) \oplus \Gamma(W^-) \oplus V_{-\infty}^\mu,$$

$$SW(\hat{a}, \hat{\phi}) = (F_{\hat{A}_0 + \hat{a}} + \sigma(\hat{\phi}, \hat{\phi}), D_{\hat{A}_0 + \hat{a}} \hat{\phi}, p^\mu \Pi i^*(\hat{a}, \hat{\phi})),$$

where i^* : the restriction to $\partial X = Y$,

Π : the Coulomb projection to V ,

$p^\mu: V \rightarrow V_{-\infty}^\mu$, the L^2 -projection.

- ▶ Write briefly as $SW: \mathcal{C}_X \rightarrow \mathcal{U} \oplus V_{-\infty}^\mu$.

- ▶ Decompose $SW: \mathcal{C}_X \rightarrow \mathcal{U} \oplus V_{-\infty}^\mu$ as $SW = L + C$,
 where L : linear & C : quadratic.
- ▶ Take a finite dimensional subspace $U \subset \mathcal{U}$, and fix $\lambda \ll 0$.
 \Rightarrow Put $U' := L^{-1}(U \times V_\lambda^\mu)$, and

$$SW_U := L + \text{pr}_{U \times V_\lambda^\mu} C: U' \rightarrow U \times V_\lambda^\mu.$$

- ▶ Fix small $\varepsilon > 0$. Let $B(U, \varepsilon) \subset U$ be the ε -ball in U .

$$\mathcal{M}_\varepsilon := SW_U^{-1}(B(U, \varepsilon) \times V_\lambda^\mu). \leftarrow \text{Almost the SW-moduli}$$

- Fix $R' \gg 1$.
 Let $B(U', R') \subset U'$ be the R' -ball.
 $S(U', R') = \partial B(U', R')$.

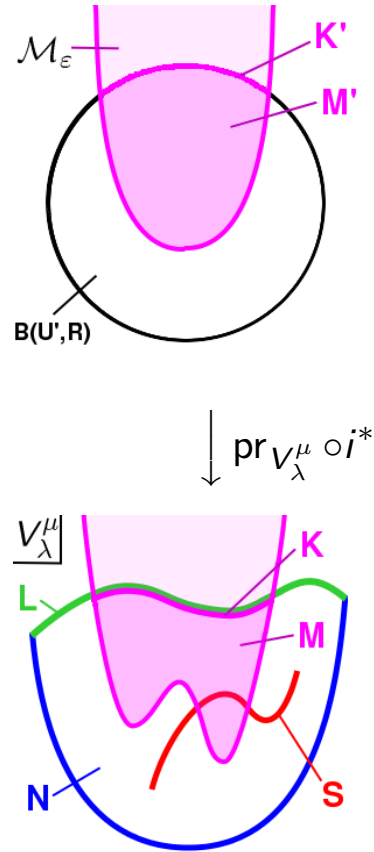
$$M' := \mathcal{M}_\varepsilon \cap B(U', R'),$$

$$K' := \mathcal{M}_\varepsilon \cap S(U', R'),$$

$$M := \text{pr}_{V_\lambda^\mu} \circ i^*(M'),$$

$$K := \text{pr}_{V_\lambda^\mu} \circ i^*(K').$$

⇒ Can find an index pair (N, L)
 s.t. $M \subset N, K \subset L$.



$$\Rightarrow SW_U: B(U', R')/S(U', R') \rightarrow (B(U, \varepsilon)/S(U, \varepsilon)) \wedge N/L.$$

$$\Rightarrow \Psi_{X, \hat{c}}: (U')^+ \rightarrow U^+ \wedge I_\lambda^\mu.$$

The relative Bauer-Furuta invariant is,

$$BF_X(\hat{c}) = [\Psi_{X, \hat{c}}] \in \left\{ \left(S^k, b^+(X), n(X, c, g) \right), SWF(Y, c) \right\}_{S^1}$$

where $k = \text{ind}_{APS} D_{\hat{A}}$.

Gluing formula for relative BF invariants

S-duality for Conley indices

- ▶ $f: M \rightarrow \mathbb{R}$, Morse function of a n -dim. mfd.
 ⇒ Morse flow φ_f .
 ⇒ The Conley index $I_f = I(\varphi_f, S)$.
- ▶ $-f \Rightarrow$ the reverse flow φ_{-f} .
 ⇒ The Conley index $I_{-f} = I(\varphi_{-f}, S)$.

Theorem (Cornea)

I_{-f} is a Spanier-Whitehead n -dual of I_f , i.e.,

$$\exists \eta: I_f \wedge I_{-f} \rightarrow S^n, \text{ } n\text{-duality map s.t.}$$

$$\eta^*: \{S^0, I_f\} \xrightarrow{\cong} \{I_{-f}, S^n\}.$$

Note For $\alpha \in \{S^0, I_f\}$, $\eta^*(\alpha)$ is given as follows:

$$S^0 \wedge I_{-f} \xrightarrow{\alpha \wedge \text{id}} I_f \wedge I_{-f} \xrightarrow{\eta} S^n.$$

Corollary

$\text{SWF}(-Y)$ is a S-dual of $\text{SWF}(Y)$.

$$(\because) \text{CSD}_{-Y} = -\text{CSD}_Y.$$

Gluing formula

- ▶ $X = X_1 \cup_Y X_2$.
- ▶ $\eta: \text{SWF}(Y) \wedge \text{SWF}(-Y) \rightarrow S^0$, the duality map.

$$\begin{aligned} \text{BF}_X &= [\Psi_X] \in \{(S^0, b^+(X), -d), S^0\}_{S^1}, \\ \text{BF}_{X_1} &= [\Psi_{X_1}] \in \{(S^0, b^+(X_1), -d_1), \text{SWF}(Y)\}_{S^1}, \\ \text{BF}_{X_2} &= [\Psi_{X_2}] \in \{(S^0, b^+(X_2), -d_2), \text{SWF}(-Y)\}_{S^1}. \\ \Rightarrow S^\bullet \wedge S^\bullet &\xrightarrow{\Psi_{X_1} \wedge \Psi_{X_2}} \text{SWF}(Y) \wedge \text{SWF}(-Y) \xrightarrow{\eta} S^\bullet. \end{aligned}$$

Theorem (Gluing formula)

$$\Psi_X \simeq \eta \circ (\Psi_{X_1} \wedge \Psi_{X_2}).$$

Cobordism

- ▶ X : a compact 4-manifold, $\partial X = (-Y_1) \cup Y_2$.

$$\begin{array}{ccc} \Psi_X \in \{(S^0, b, -d), \text{SWF}(-Y_1) \wedge \text{SWF}(Y_2)\}_{S^1} & & \\ \downarrow & & \downarrow \begin{array}{c} S\text{-duality} \\ \cong \end{array} \\ \mathcal{D}(X) \in \{(\text{SWF}(Y_1), b, -d), \text{SWF}(Y_2)\}_{S^1} & & \end{array}$$

A cobordism X gives a morphism $\mathcal{D}(X)$ between SWF's.

Theorem

- ▶ $X_a: \partial X_a = (-Y_1) \cup Y_2$ & $X_b: \partial X_b = (-Y_2) \cup Y_3$.
- ▶ $X = X_a \cup_{Y_2} X_b$.

$$\Rightarrow \mathcal{D}(X) = \Sigma^{b^+(X_a), -d(X_a)} \mathcal{D}(X_b) \circ \mathcal{D}(X_a)$$

Applications

to negative definite manifolds

Theorem A (Donaldson)

X : closed ori. 4-mfd with negative definite form Ψ_X

$\Rightarrow \Psi_X \cong \text{diagonal}$.

Proof by [Bauer-Furuta]

The finite dim approx. of the monopole map:

$$f: S^V := (\mathbb{R}^m \oplus \mathbb{C}^{n+s})^+ \rightarrow (\mathbb{R}^m \oplus \mathbb{C}^n)^+.$$

This is S^1 -equivariant and $\deg f|_{(S^V)^{S^1}} = 1$.

Lemma

For f as above, $s \leq 0$.

(\because) Use tom Dieck's character formula.

Proof of Theorem A.

$$0 \geq s = \text{ind}_{\mathbb{C}} D = \frac{c^2 + b_2(X)}{8}.$$

$\therefore \forall c$: characteristic $c^2 + b_2(X) \leq 0$.

\Rightarrow Diagonal.

[Elkies]

□

Question

Does an analogue of Theorem A for 4-mfd **with boundary**?

→ **Yes.**

Theorem (Froyshov)

X : compact ori. 4-mfd, $\partial X =$ the Poincaré 3-sphere.

If $\Psi_X \cong m(-1) \oplus J$, where J : negative definite **even**,

$$\Rightarrow J = 0 \text{ or } J = -E_8.$$

- ▶ Froyshov proved this by the invariant he defined.
- ▶ **This can be proved by using SWF.**

- ▶ X : negative definite, $\partial X = Y$. The monopole map f satisfies

$$[f] \in \{(\mathbb{C}^s)^+, \text{SWF}(Y, c)\}_{S^1} \ \& \ \deg f^{S^1} = 1.$$

$$s(Y, c) := \max \left(s \mid \exists f \text{ s.t. } \left\{ \begin{array}{l} [f] \in \{(\mathbb{C}^s)^+, \text{SWF}(Y, c)\}_{S^1} \\ \deg f^{S^1} = 1 \end{array} \right\} \right).$$

- ▶ **Recall**, if Y is the Poincaré 3-sphere $\Rightarrow \text{SWF}(Y) = \mathbb{C}^+$.

Then, $s(Y) = 1$.

$$\because f \in \{(\mathbb{C}^s)^+, \mathbb{C}^+\}_{S^1} \ \& \ \deg f^{S^1} = 1 \Rightarrow s - 1 \leq 0.$$

Theorem

X : compact ori. negative definite, $\partial X = Y$.

For \forall characteristic c

$$\frac{b_2(X) + c^2}{8} \leq s(Y, c),$$

Proof.

The monopole map f for c satisfies

$$[f] \in \{(\mathbb{C}^k)^+, \text{SWF}(Y, c)\}_{S^1} \text{ \& } \deg f^{S^1} = 1,$$

where $k = (c^2 + b_2)/8$.

Therefore $k \leq s(Y, c)$. □

Theorem (Froyshov)

X : compact ori. 4-mfd, $\partial X =$ the Poincaré 3-sphere.

If $\Psi_X \cong m(-1) \oplus J$, where J : negative definite **even**,

$$\Rightarrow J = 0 \text{ or } J = -E_8.$$

Proof

- ▶ Note that $c = (\overbrace{1, \dots, 1}^m, 0, \dots, 0)$ is a characteristic.
- $\Rightarrow \text{rank } J = b_2 - m = b_2 + c^2 \leq 8s(Y) = 8$.
- $\therefore J = 0$ or $J = -E_8$. □

Question

What is the relation between $s(Y)$ & Froyshov's invariants?